7/26/05:

Today we have 4 realizations from section 1: afternoon of Jul 26, morning and afternoon of Jul 27, and morning of Jul 28.

Optimal: points=30, threshold=1000 for afternoon of Jul 26

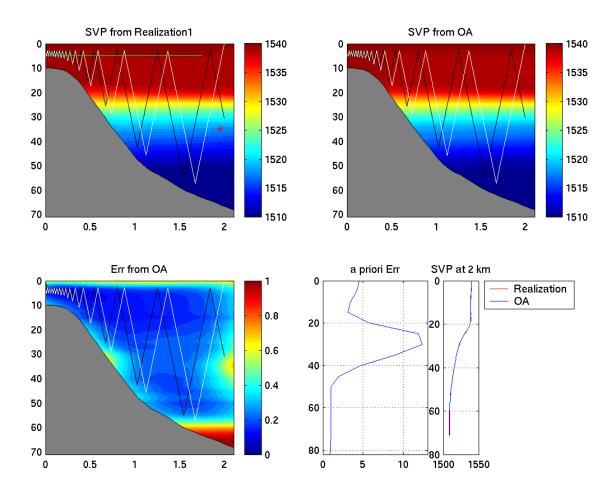
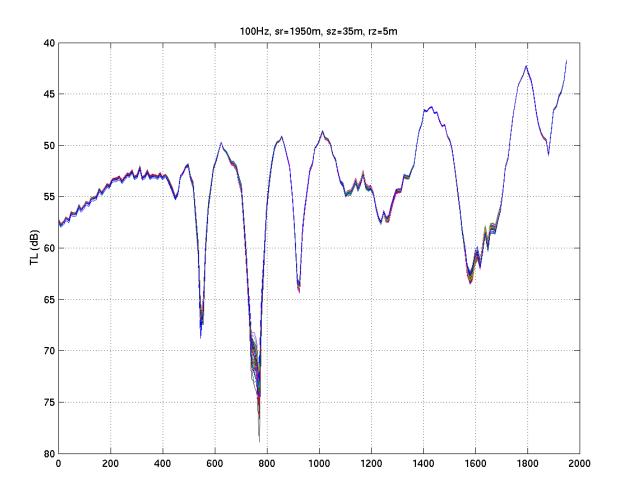


Figure 55: Yoyo control implementation. Afternoon 7/26/05. true_sound_faf05_jul26_06_day.5_2_sec1.mat. Black line is the forward path; White line is the backward path. Note that to avoid bottom AUV turns around at 5 m above bottom.

Optimal: points=30, threshold=1000 for morning of Jul 27 Optimal: points=30, threshold=1000 for afternoon of Jul 27 Optimal: points=30, threshold=1000 for morning of Jul 28



 $\label{eq:figure 56:Afternoon 7/26/05. true_sound_faf05_jul26_06_day.5_2_sec1.mat.}$

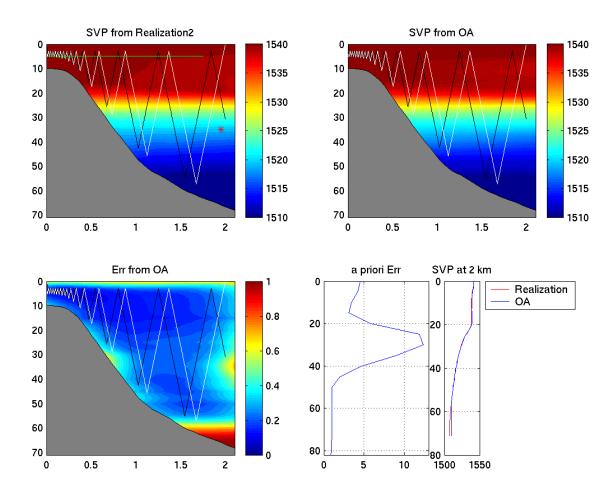
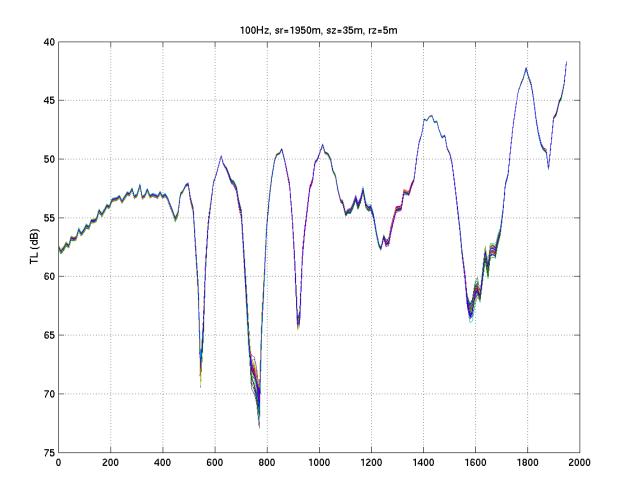


Figure 57: Yoyo control implementation. Morning 7/27/05. true_sound_faf05_jul26_06_day.5_2_sec1.mat. Black line is the forward path; White line is the backward path. Note that to avoid bottom AUV turns around at 5 m above bottom.



 $Figure~58:~Morning~7/27/05.~true_sound_faf05_jul26_06_day.5_2_sec1.mat.$

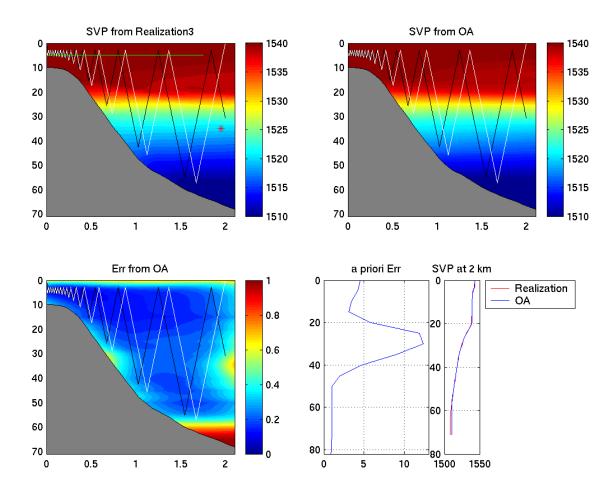
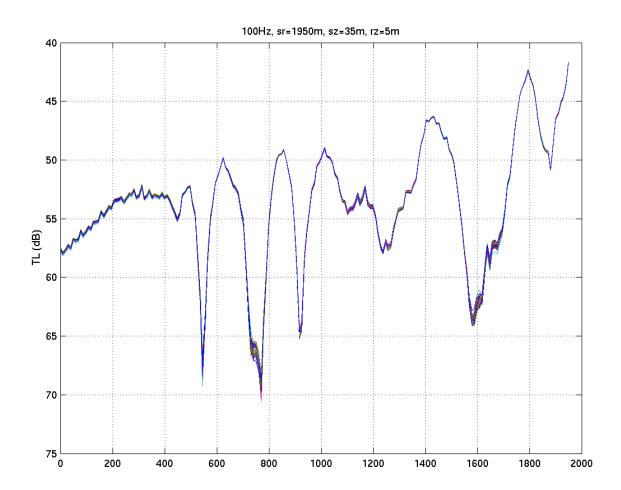


Figure 59: Yoyo control implementation. Afternoon 7/27/05. true_sound_faf05_jul26_06_day.5_2_sec1.mat. Black line is the forward path; White line is the backward path. Note that to avoid bottom AUV turns around at 5 m above bottom.



 $\label{eq:figure 60:Afternoon 7/27/05. true_sound_faf05_jul26_06_day.5_2_sec1.mat.}$

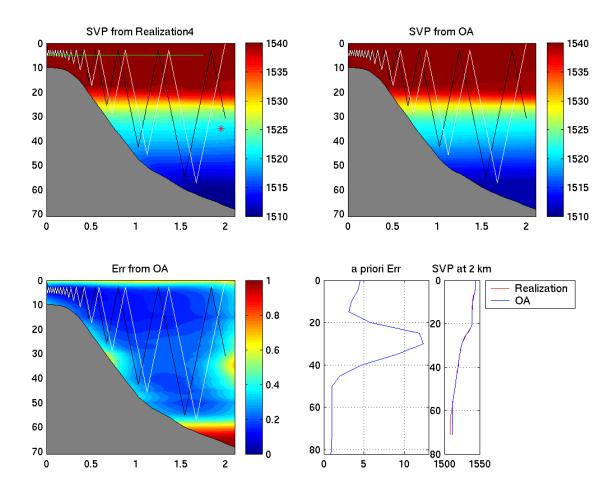
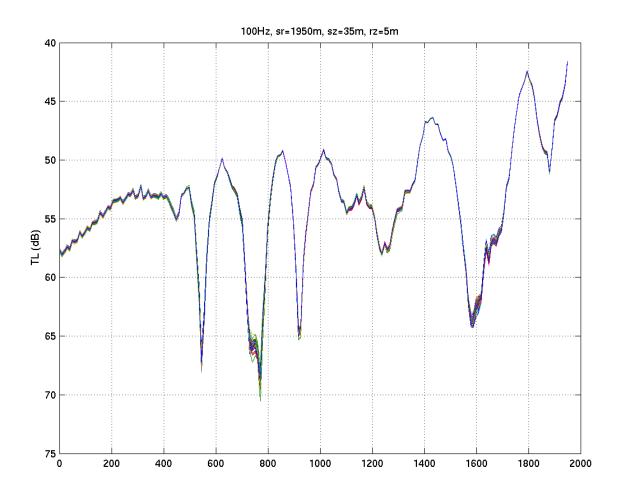
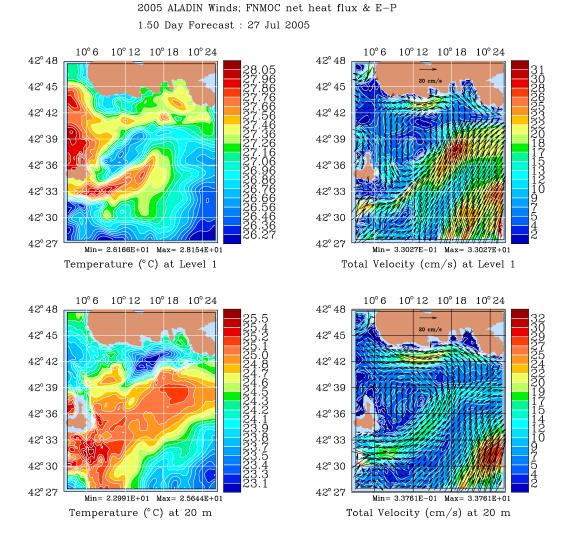


Figure 61: Yoyo control implementation. Morning 7/28/05. true_sound_faf05_jul26_06_day.5_2_sec1.mat. Black line is the forward path; White line is the backward path. Note that to avoid bottom AUV turns around at 5 m above bottom.



 $Figure~62:~Morning~7/28/05.~true_sound_faf05_jul26_06_day.5_2_sec1.mat.$



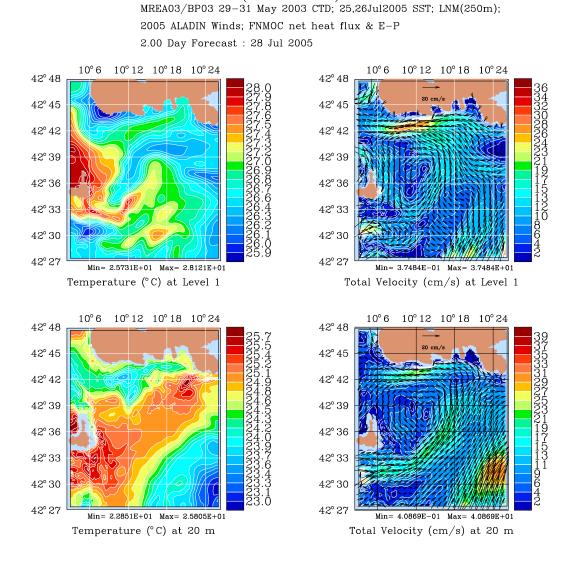
(run 139)

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Figure 63: Temperature and current fields at 0 and 20m, for 7/27/05 afternoon. Elba area.



(run 139)

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Figure 64: Temperature and current fields at 0 and 20m, for 7/28/05 morning. Elba area.